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**PATENT APPLICATION TRANSMITTAL LETTER**  
(Large Entity)

Docket No.  
0750RF-051

TO THE ASSISTANT COMMISSIONER FOR PATENTS

Transmitted herewith for filing under 35 U.S.C. 111 and 37 C.F.R. 1.53 is the patent application of:

Joseph A. Henke et al.

For: **ELECTRO-MECHANICAL WIRELINE ANCHORING SYSTEM**

Enclosed are:

- ☒ Certificate of Mailing with Express Mail Mailing Label No. **EL139164419US**
- ☒ **Thirteen (13)** sheets of drawings.
- ☐ A certified copy of a \_\_\_\_\_ application.
- ☒ Declaration ☐ Signed. ☒ Unsigned.
- ☒ Power of Attorney
- ☐ Information Disclosure Statement
- ☐ Preliminary Amendment
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**CLAIMS AS FILED**

For	#Filed	#Allowed	#Extra	Rate	Fee
<b>Total Claims</b>	31	- 20 =	11	x \$18.00	\$198.00
<b>Indep. Claims</b>	3	- 3 =	0	x \$78.00	\$0.00
<b>Multiple Dependent Claims (check if applicable)</b> <input type="checkbox"/>					\$0.00
<b>BASIC FEE</b>					\$710.00
<b>TOTAL FILING FEE</b>					\$908.00

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Dated: **October 2, 2000**

*Charles D. Gunter, Jr.*  
\_\_\_\_\_  
Signature

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CC:

S P E C I F I C A T I O N

Docket No. 0750RF-051

TO ALL WHOM IT MAY CONCERN:

BE IT KNOWN that we, Joseph A. Henke, David S. Wesson, and Phil Phelps, citizens of the United States of America, residing in the State of Texas, have invented new and useful improvements in an

**ELECTRO-MECHANICAL WIRELINE ANCHORING SYSTEM**

of which the following is a specification:

CERTIFICATE OF MAILING BY "EXPRESS MAIL" UNDER 37 CFR § 1.10

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Sarah Horner

*Sarah Horner*

## BACKGROUND OF THE INVENTION

### 1. Field of the Invention:

The present invention relates generally to wireline assemblies used in wellbore operations and, specifically to an electro-mechanical anchoring system for a wireline tool string.

### 2. Description of the Prior Art:

During the production of hydrocarbons from subterranean well formations, a casing string is typically cemented in order to consolidate the wellbore. Typically, a tubing string extends from the well surface to the required depth in the wellbore in order to flow hydrocarbon fluids from the subterranean formation to the surface.

A perforating gun assembly is lowered from the surface and positioned within the casing adjacent the producing interval. The gun may be run on a tubing string or may be suspended from a wireline from the surface. In the case of the wireline tool, an electrical current transmitted through the wireline can be used to actuate the perforating guns in order to perforate the surrounding well casing and allow the flow of fluids to the well surface.

In certain types of wellbore conditions, it may be necessary to provide additional means for holding the wireline tool string in place downhole during underbalanced perforating and/or flowing of the well after perforating.

1 While various mechanical devices have been utilized in the  
2 prior art, most were overly complicated and were sometimes less  
3 than reliable in operation.  
4

5 A need exists for an apparatus to provide a means for holding  
6 a wireline tool string in place downhole during underbalanced  
7 wellbore operations.  
8

9 A need also exists for such a device which can be electro-  
10 mechanically actuated and which also features a back-up manual  
11 release.  
12

13 A need exists for such a device which will positively indicate  
14 when the "set" position has been achieved.  
15

16 A need also exists for such a device which is simple in design  
17 and relatively economical to manufacture.  
18



1 mechanical release mechanism is utilized to release the wireline  
2 assembly mechanically.

3  
4 The back-up release mechanism is actuated by slacking off  
5 tension on the wireline to telescope the tool downwardly within  
6 itself. The downward telescoping action engages collet fingers  
7 with a releasing neck on a collet latch sub provided as a part of  
8 the assembly. An upward pull on the wireline cable then shears  
9 one or more shear pins and allows the back-up release mechanism to  
10 release the tool as tension continues to be applied upwardly.

11  
12 In a preferred embodiment, the electro-mechanical wireline  
13 assembly of the invention includes an upper connecting means for  
14 connecting the assembly to a wireline leading to the well surface.  
15 A lower connecting means is provided for engaging a wireline tool  
16 such as a perforating gun assembly. An outer mandrel is connected  
17 to the lower connecting means. An inner mandrel is carried at  
18 least partly within the outer mandrel and is capable of axial  
19 movement relative thereto. A slip gripping assembly is carried on  
20 the outer mandrel and includes a plurality of gripping slips  
21 normally biased radially inward but movable radially outward for  
22 engaging a surrounding wellbore and holding a wireline tool string  
23 in place in the wellbore.

24  
25 An electric motor assembly is carried on the wireline assembly  
26 between the upper connecting means and the lower connecting means.  
27 The electric motor assembly is actuatable by an electric current  
28 supplied from the well surface through the wireline to effect axial  
29 movement of the inner mandrel relative to the outer mandrel to

expand the gripping slips in a radial direction between a start position and a set position. Switch means, included as a part of the electric motor assembly, are provided to reverse the direction of axial movement of the inner mandrel relative to the outer mandrel to retract the gripping slips and return the slips to the start position. Preferably, the assembly further comprises a back-up manual release means for manually retracting the gripping slips radially inward upon completion of wellbore operations.

Additional objects, features and advantages will be apparent in the written description which follows.

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100
1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63	64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94	95	96	97	98	99	100

1                   **BRIEF DESCRIPTION OF THE DRAWINGS**

2

3           **Figures 1A-1D** are successive portions of a sectional view of  
4 the electro-mechanical wireline assembly of the invention in the  
5 running-in position and with a wireline tool assembly being shown  
6 attached thereto in dotted lines;

7

8           **Figures 2A-2D** are successive portions of a sectional view  
9 similar to Figures 1A-1D but showing the wireline assembly of the  
10 invention in the set position;

11

12           **Figures 3A-3D, 4A-4D and 5A-5D** are similar successive  
13 sectional views but showing the various steps involved in the  
14 mechanical back-up release operation; and

15

16           **Figure 6** is an electrical schematic of the electrical circuit  
17 and switch means used to power the electric motor assembly to  
18 extend and retract the gripping slips which engage the surrounding  
19 wellbore.



## DETAILED DESCRIPTION OF THE INVENTION

Turning first to Figures 1A-1D, there is shown an electro-mechanical wireline assembly of the invention designated generally as 11. The assembly 11 is used for anchoring a wireline tool (shown in dotted lines as "T" in Figure 1D) in place in a wellbore when conditions warrant, such as during underbalanced well conditions. The wireline tool string "T" could comprise, for example, a well perforating gun string of the type known in the art or a logging string for production logging of the flowing well. The assembly includes a lower connecting means, such as the lower adapter 13 (Figure 1D) for connection to the wireline tool string which depends downwardly therefrom. The lower adapter 13 is a generally cylindrical body having an internal bore 15 and an externally threaded upper extent 17. A slip gripping assembly 19 carrying a plurality of gripping slips 21 threadedly engages the threaded extent 17 of the lower adapter 13. The slip gripping assembly 19 and gripping slips 21 surround an outer mandrel 23. The gripping slips 21 are pivotable outward between the running-in or start position shown in Figure 1D and the set or gripping position shown in Figure 2D. The gripping slips are initially biased inwardly by means of the coiled springs 25 which circumscribe the assembly. Preferably, three gripping slips 21 are circumferentially spaced approximately 120° apart on the exterior surface of the outer mandrel.

As shown in Figure 1D, a tubular slip guide 27 is carried about the outer mandrel 23 and has a tapered lower extent 29 which functions as a ramp or spreader surface for contacting a mating

1 tapered surface 30 of each gripping slip 21. The slip guide 27  
2 terminates upwardly in a series of collet fingers 31 (see Figure  
3 2D) which are initially retained in a running-in position by an  
4 interior surface 33 (Figure 2D) of a collet latch housing 35. The  
5 collet latch housing 35 is a tubular member which is initially  
6 connected to the slip guide 27 by a temporary connecting means such  
7 as a plurality of shear pins 37. The collet latch housing 35 also  
8 has an internal profile 39 for receiving the slip guide collet  
9 fingers 31 upon upward axial movement of the collet latch housing  
10 35. As also seen in Figure 1D, the collet fingers 31 of the slip  
11 guide 27 are located within mating slots 41-43 machined in the  
12 exterior surface of the outer mandrel 23. The collet latch housing  
13 35 terminates upwardly in an outwardly tapered fishing neck region  
14 45 (Figure 1C).

15  
16 The outer mandrel 23 has a series of window openings 47 for  
17 receiving a retaining means such as retaining dogs 50. Other  
18 retaining means such as a plurality of retaining balls could also  
19 be utilized. The retaining dogs 50 initially prevent downward  
20 axial movement of a tubular collet housing 51. The tubular collet  
21 housing 51 terminates at a lower extent in collet fingers 53 which  
22 are engageable upon downward axial movement with the fishing neck  
23 45 of the collet latch housing 35.

24  
25 The collet housing 51 has an externally threaded upper extent  
26 55 for engaging a mating internally threaded surface 57 of an outer  
27 motor housing 59. The outer motor housing 59 is a generally  
28 tubular body having an externally threaded upper extent 61 (Figure  
29 1B) which threadedly engages the internally threaded surface 63 of

1 a coiled wire housing 65. The coiled wire housing 65 is, in turn,  
2 a generally tubular body having an internally threaded extent 67  
3 (Figure 1A) for threadedly engaging the lower extent 69 of a top  
4 adapter member 71. The top adapter 71, as well as certain of the  
5 other components of the firing assembly are commercially available  
6 from Owen Oil Tools of Fort Worth, Texas, and will be familiar to  
7 those skilled in the relevant arts. A wireline collar locator  
8 assembly (not shown) would typically be attached to the top adapter  
9 71. A conventional electrical lead in 73 is in electrical contact  
10 through the wireline leading to the well surface and to a suitable  
11 power supply located at the surface. The lead in 73 (Figure 1A)  
12 has a length of coiled wire 75 located within the tubular housing  
13 65, the coils, being of sufficient length to allow a degree of  
14 axial movement of the internal components of the wireline assembly,  
15 as will be explained further.

16  
17 The coiled wire 75 is connected by means of a conventional  
18 lead-in 77 to a connecting assembly including the upper portion 79  
19 and lower portion 81. The upper portion 79 has a bore 80  
20 containing contact spring (Figure 1B). Bushing 84 connects the  
21 opposing ends 86, 88 of the conductors which allow the follow up  
22 electrical current to the terminal 90. Terminal 90 is connected by  
23 means of an electrical lead 83 with an electric motor assembly 85  
24 located within tubular member 87. The tubular member 87 is  
25 threadedly connected at an upper extent 89 to the lower portion 81  
26 of the connecting assembly and at the lower extent 91 (Figure 1C)  
27 thereof to a motor frame 93.

1       The application of an electrical current to the motor assembly  
2       85 acts through bearing assembly 95 and ball nut assembly 97 to  
3       turn screw 99. The externally threaded screw 99 connects through  
4       a ball nut adapter 101 to an upper extent 103 of an inner mandrel  
5       105. The inner mandrel 105 passes through mating bores in the  
6       motor frame 93 and outer mandrel 23 and terminates at a lower  
7       extent 107 (Figure 1D) which is received within a mating bore 109  
8       provided in the lower adapter 13. The inner mandrel 105 also has  
9       an internal bore 111 which allows an electrical lead 113 to pass  
10      through the interior of the inner mandrel to the bore 15 of the  
11      lower adapter 13. A plug assembly 115 is provided of conventional  
12      design for electrical connection to a depending wireline tool, such  
13      as a perforating gun string (shown in dotted lines in Figure 1D.)  
14

15       Referring to Figure 1A, the electro-mechanical wireline  
16      assembly as shown in the running-in position. As previously  
17      discussed, the perforating gun assembly "T" in Figure 1D would be  
18      attached to the lower adapter 13 and a wireline collar locator  
19      assembly would be attached to the top adapter 71. The weight of the  
20      tool string is carried through the tool from the lower adapter body  
21      13 (Figure 1D) which is threaded to the outer mandrel 23 which, in  
22      turn, is threaded into the motor frame 93. The bottom extent 117  
23      of the motor frame 93 rests on top of the externally threaded upper  
24      extent 55 (Figure 1C) of the collet housing 51. The collet housing  
25      51 is threadedly connected to the outer motor housing 59. The  
26      outer motor housing 59 is threaded into the coiled wire housing 65  
27      which, in turn, is connected to the top adapter 71. The top  
28      adapter 71 would be connected through the collar locator (not  
29      shown) and wireline to the well surface.

Turning to Figures 2A-2D, the wireline assembly would be run into the wellbore to the desired setting depth. An electrical current is then supplied to the motor assembly 85 to turn the screw 99 within the ball nut assembly 97 (Figure 2C) and move the ball nut assembly 97 axially downward. The ball nut adapter 101, being attached to the ball nut assembly at the upper extent thereof and the inner mandrel 105 at the lower extent thereof transmits the downward axial movement to the inner mandrel. The slip guide 29 (Figure 2D) is engaged to the inner mandrel 105 by the collet fingers 31. The collet fingers 31 are held in the slots 41 provided on the exterior of the inner mandrel 105 by the collet latch housing 35. As the inner mandrel 105 moves axially downward, the slip guide 29 is forced beneath the gripping slips 21 to move the slips 21 radially outward against the casing/tubing of the wellbore. Contact between the teeth of the gripping slips 21 and the surrounding casing/tubing sets the tool in position. Once the tool is set, tension is pulled on the wireline leading to the well surface in order to verify that the tool is holding. An electrical current can then be passed down the assembly to the depending perforating gun assembly in order to fire the guns. The well can then be flowed as desired for cleanup.

After the pressure is stabilized, the wireline assembly can be released by sending an electrical current back to the motor assembly 85 to turn the screw 99 in the opposite direction (from setting rotation) to move the slip guide 29, inner mandrel 105, ball nut adapter 101 and ball nut assembly 97 back to the running-in position.

Referring to Figure 6, a circuit diagram for a control circuit providing switching control for the motor employed in setting the wireline assembly is depicted. Motor M1 may be any of a number of commercially available motors, such as Globe model 43A10-5. An operational amplifier (op-amp) U1 is employed to control switching of the motor M1. The direction of current through motor M1 is controlled by inductively-switched switching device (relay) S1; inductively-switched switching device S2 controls whether power is transmitted to the motor. Power is supplied to the motor M1 from an input connected to diode D11 and returned through an output connected to diode D12.

Initially, during run-in, power through diode D11 is connected through switching device S2 and switching device S1, which is configured to pass the power in a first polarity, to motor M1. Power out of the motor M1 is connected to the negative feedback loop (resistor R7:1) of op-amp U1 through resistor R8:1, allowing the current drawn by motor M1 to be monitored. When the motor M1 binds (and begins drawing significantly more current) during setting of the wireline assembly, op-amp U1 trips switching device S2 to disconnect the applied input power from motor M1, which in turn causes switching device S1 to trip, reversing the polarity of the connection of motor M1 to the power connections at diodes D11 and D12. Op-amp U1 and switching device S2 may then be reset by disconnecting and reconnecting power to the control circuit. Power is therefore again transmitted to motor M1 from diode D11, but with the opposite polarity as before due to the prior tripping of switching device S1. Subsequent cycling (disconnect/reconnect) of

1 power to the control circuit may be employed to restore switching  
2 device S1 to its original position.  
3

4 It should be noted that only the positive power connection  
5 (through diode D11) is employed to directly control motor  
6 switching, although the negative power connection through the diode  
7 D12 is employed to sense current drawn by motor M1. This allows  
8 the negative power connection from the surface to the employed to  
9 fire the perforating guns, utilizing circuitry not shown in Figure  
10 6.  
11

12 While the tool has been described as being operated with an  
13 electric current supplied from a power source at the well surface,  
14 it will be appreciated that it could be modified to operate with a  
15 power source located downhole on the tool, as well.  
16

17 If, for some reason, an electrical current cannot be  
18 transmitted to the motor assembly 85 after firing the perforating  
19 guns, a mechanical back-up release mechanism is utilized.  
20

21 Figures 3A-3D, 4A-4D and 5A-5D illustrate the mechanical  
22 release operation. The wireline assembly begins the procedure in  
23 the set position illustrated in Figures 2A-2D. The retaining dogs  
24 (50 in Figure 2C) prevent any downward movement of the collet  
25 housing 51, and in turn, the outer portions of the tool until the  
26 tool is in the set position. With the tool in the set position,  
27 the recess 119 in the inner mandrel 105 is positioned below the  
28 retaining dogs 50, allowing the dogs 50 to move radially inward  
29 when the collet housing 51 is moved axially downward. This allows

1 the collet fingers 53 of the collet housing 51 to engage the  
2 fishing neck 45 of the collet latch housing 35. An upward pull on  
3 the wireline from the well surface then acts to shear the shear  
4 pins 37 (Figure 2D) which initially connect the slip guide 27 to  
5 the collet latch housing 35.

6  
7 After shearing the pins 37 (Figure 4D), upward movement on the  
8 wireline pulls the collet latch housing 51 upwardly to the allow  
9 the collets on the slip guide 27 to spring out into the internal  
10 recess 39 of the collet latch housing 35. The slip guide 27 is  
11 then pulled axially upward from beneath the gripping slips. The  
12 gripping slips 21 are then retracted radially inward by means of  
13 the biasing force exerted by coiled springs 25 to the running-end  
14 position. Once the slips are collapsed, the tools is released and  
15 can be retrieved on the wireline from the wellbore. The weight of  
16 the tool string is carried out of the hole in the same manner as  
17 depicted with respect to the initial running-in position  
18 illustrated in Figures 1A-1D.

19  
20 An invention has been provided with several advantages. The  
21 electro-mechanical wireline assembly of the invention allows a  
22 wireline tool string to be securely anchored in position within a  
23 wellbore even during severely underbalanced well conditions. The  
24 wireline assembly is simple in design and relatively economical to  
25 manufacture and is extremely reliable in operation. Because an  
26 electric motor assembly is used to actuate the slip gripping  
27 operation, the operator at the well surface knows with certainty  
28 when the gripping operation is complete because the motor stalls  
29 out. The desired wellbore operations, such as firing of the



1 perforating gun assembly can then be safely carried out. The  
2 electric motor assembly also provides a convenient mechanism for  
3 the reverse movement of the slip gripping assembly. If, for some  
4 reason, the electric motor assembly cannot be reactuated, a simple  
5 mechanical release mechanism is provided.

7        While the invention has been shown in only one of its forms,  
8        it is not thus limited but is susceptible to various changes and  
9        modifications without departing from the spirit thereof.

[illegible]

What is claimed is:

1. An electro-mechanical wireline assembly for anchoring a wireline tool string in place in a well bore during underbalanced well conditions, the assembly comprising:

upper connecting means for connecting the assembly to a wireline leading to the well surface;

lower connecting means for engaging a wireline tool;

an outer mandrel connected to the lower connecting means;

an inner mandrel carried at least partly within the outer mandrel and capable of axial movement relative thereto;

a slip gripping assembly carried on the outer mandrel and including a plurality of gripping slips normally biased radially inward but movable radially outward for engaging a surrounding well bore and holding the wireline tool string in place in the well bore;

an electric motor assembly carried on the wireline assembly between the upper connecting means and the lower connecting means, the electric motor assembly being actuable by an electric current supplied from the well surface through the wireline to effect axial movement of the inner mandrel relative to the outer mandrel to expand the gripping slips in a radial direction between a start position and a set position;

switch means included as a part of the electric motor assembly for reversing the direction of axial movement of the inner mandrel relative to the outer mandrel to retract the gripping slips and return the slips to the start position; and

wherein the assembly further comprises back-up manual release means for manually retracting the gripping slips radially inward upon completion of wellbore operations.

2. The electro-mechanical wireline assembly of claim 1, wherein the lower connecting means is connected to a wireline tool selected from the group consisting of a well perforating gun assembly and a well production logging assembly.

3. The electro-mechanical wireline assembly of claim 2, wherein the slip gripping assembly includes at least three gripping slips located 120 degrees apart on an exterior surface of the outer mandrel.

4. The electro-mechanical wireline assembly of claim 3, wherein the electric motor assembly includes an electric motor and a screw driven by the electric motor to effect axial movement of the inner mandrel relative to the outer mandrel.

5. The electro-mechanical wireline assembly of claim 4, wherein the screw is drivable in either a forward or reverse direction by the application of electric current through the wireline from the well surface to the electric motor.

1 6. The electro-mechanical wireline assembly of claim 5, further  
2 comprising:  
3

4 a collet housing including a plurality of downwardly extending  
5 collet fingers carried about the outer mandrel at an upper extent  
6 thereof, the collet housing being threadedly engaged to an outer  
7 motor housing.  
8

9 7. The electro-mechanical wireline assembly of claim 6, wherein the  
10 outer motor housing is threadedly engaged to a coiled wire housing  
11 which, in turn, is threadedly engaged to the top adapter.  
12

13 8. The electro-mechanical wireline assembly of claim 7, wherein the  
14 collet housing is initially retained in a running in position by at  
15 least one retaining dog carried in an opening provided on the outer  
16 mandrel adjacent the upper extent thereof.  
17

18 9. The electro-mechanical wireline assembly of claim 8, wherein the  
19 inner mandrel is provided with a recess for receiving the at least  
20 one retaining dog, movement of the retaining dog into the recess  
21 serving to allow movement of the collet housing axially downward  
22 relative to the outer mandrel whereby the collet fingers can engage  
23 a collet latch housing.  
24

1 10. The electro-mechanical wireline assembly of claim 9, wherein  
2 the collet latch housing is connected to a slip guide which  
3 underlies the gripping slips in the set position, the connection to  
4 the slip guide being severable by upward axial movement of the  
5 collet housing, thereby allowing the slip guide to be moved from  
6 beneath the gripping slips whereby the gripping slips can be  
7 returned to the start position.  
8

9 11. An electro-mechanical wireline assembly for anchoring a  
10 perforating gun assembly in place in a well bore during  
11 underbalanced well conditions, the assembly comprising:

12  
13 upper connecting means for connecting the assembly to a wireline  
14 leading to the well surface;

15  
16 lower connecting means engaged to a perforating gun assembly  
17 including at least one wireline actuated perforating gun;

18  
19 an outer mandrel connected to the lower connecting means;

20  
21 an inner mandrel carried at least partly within the outer mandrel  
22 and capable of axial movement relative thereto;

23  
24 a slip gripping assembly carried on the outer mandrel and including  
25 a plurality of gripping slips normally biased radially inward but  
26 movable radially outward for engaging a surrounding well bore and  
27 holding the wireline tool string in place in the well bore;  
28

an electric motor assembly carried on the wireline assembly between the upper connecting means and the lower connecting means, the electric motor assembly being actuatable by an electrical current supplied from the well surface through the wireline to effect axial movement of the inner mandrel relative to the outer mandrel to expand the gripping slips in a radial direction between a start position and a set position;

switch means provided as a part of the electric motor assembly and actuatable to move the inner mandrel in a reverse axial direction in response to an electrical current supplied through the wireline from the well surface to retract the gripping slips and return the slips to the start position.

12. The electro-mechanical wireline assembly of claim 11, wherein the slip gripping assembly includes at least three gripping slips located 120 degrees apart on an exterior surface of the outer mandrel.

13. The electro-mechanical wireline assembly of claim 12, wherein the electric motor assembly includes an electric motor and a screw driven by the electric motor and connected to the inner mandrel to effect axial movement of the inner mandrel relative to the outer mandrel.

14. The electro-mechanical wireline assembly of claim 13, wherein the screw is drivable in either a forward or reverse direction by the application of electric current through the wireline from the well surface to the electric motor.

1 15. The electro-mechanical wireline assembly of claim 14, further  
2 comprising:

3  
4 a collet housing including a plurality of downwardly extending  
5 collet fingers carried about the outer mandrel at an upper extent  
6 thereof, the collet housing being threadedly engaged to an outer  
7 motor housing.

8  
9 16. The electro-mechanical wireline assembly of claim 15, wherein  
10 the outer motor housing is threadedly engaged to a coiled wire  
11 housing which, in turn, is threadedly engaged to the top adapter.

12  
13 17. The electro-mechanical wireline assembly of claim 16, wherein  
14 the collet housing is initially retained in a running in position  
15 by at least one retaining dog carried in an opening provided on the  
16 outer mandrel adjacent the upper extent thereof.

17  
18 18. The electro-mechanical wireline assembly of claim 17, wherein  
19 the inner mandrel is provided with a recess for receiving the at  
20 least one retaining dog, movement of the retaining dog into the  
21 recess serving to allow movement of the collet housing axially  
22 downward relative to the outer mandrel whereby the collet fingers  
23 can engage a collet latch housing.

24  
25 19. The electro-mechanical wireline assembly of claim 18, wherein  
26 the collet latch housing is  
27 connected to a slip guide which underlies the gripping slips in the  
28 set position, the connection to the slip guide being severable by  
29 upward axial movement of the collet housing and the collet latch

housing, thereby allowing the slip guide to be moved from beneath the gripping slips whereby the gripping slips can be returned to the start position.

20. The electro-mechanical wireline assembly of claim 19, wherein the slip guide includes upper collet fingers which are initially retained in a running in position by an interior surface of the collet latch housing and wherein the collet latch housing has an internal profile for receiving the slip guide collet fingers upon upward axial movement effected by the engagement of the collet housing collet fingers with the collet latch housing.

21. The electro-mechanical wireline assembly of claim 20, wherein the collet latch housing is initially connected to the slip guide by a plurality of shear screws, the shear screws being severable by upward tension exerted on the collet latch housing by the collet housing.

22. A method for anchoring a wireline perforating assembly in place in a well bore during underbalanced well conditions, the method comprising the steps of:

providing an electro-mechanical wireline assembly having upper connecting means for connecting the assembly to a wireline leading to the well surface;

connecting a wireline perforating assembly to a lower connecting means provided on the electro-mechanical wireline assembly;



1 providing an outer mandrel connected to the lower connecting means;

2  
3 providing an inner mandrel carried at least partly within the outer  
4 mandrel and capable of axial movement relative thereto;

5  
6 providing a slip gripping assembly carried on the outer mandrel and  
7 including a plurality of gripping slips normally biased radially  
8 inward but movable radially outward for engaging a surrounding well  
9 bore and holding the wireline tool string in place in the well  
10 bore;

11  
12 providing an electric motor assembly carried on the wireline  
13 assembly between the upper connecting means and the lower  
14 connecting means, the electric motor assembly being actuable by an  
15 electric current supplied from the well surface through the  
16 wireline to effect axial movement of the inner mandrel relative to  
17 the outer mandrel to expand the gripping slips in a radial  
18 direction between a start position and a set position;

19  
20 providing switch means included as a part of the electric motor  
21 assembly for reversing the direction of axial movement of the inner  
22 mandrel relative to the outer mandrel to retract the gripping slips  
23 and return the slips to the start position;

24  
25 running the electro-mechanical wireline assembly into position at  
26 a subterranean location within the well bore;

supplying an electrical current to the electric motor assembly to move the inner radial mandrel axially relative to the outer mandrel and thereby set the gripping slips;

actuating the perforating gun assembly by an electric current supplied from the well surface;

reversing the direction of movement of the inner mandrel relative to the outer mandrel by the application of an additional electrical current from the well surface through the wireline, said movement serving to allow the gripping slips to be retracted radially inward to the start position; and

retrieving the electro-mechanical wireline assembly and perforating gun assembly to the well surface.

23. The method of claim 22, wherein the electric motor assembly includes an electric motor and a screw driven by the electric motor to effect axial movement of the inner mandrel relative to the outer mandrel.

24. The method of claim 22, wherein the switch means is actuated to drive the screw in either a forward or reverse direction by the application of electric current through the wireline from the well surface to the electric motor.

25. The method of claim 24, wherein the electro-mechanical wireline assembly is further provided with back-up manual release means for

1 manually retracting the gripping slips radially inward upon  
2 completion of wellbore operations.

3  
4 26. The method of claim 25, wherein the back-up manual release  
5 includes a collet housing including a plurality of downwardly  
6 extending collet fingers carried about the outer mandrel at an  
7 upper extent thereof, the collet housing being threadedly engaged  
8 to an outer motor housing, the outer motor housing being threadedly  
9 engaged to a coiled wire housing which, in turn, is threadedly  
10 engaged to the top adapter.

11  
12 27. The method of claim 26, wherein the collet housing is initially  
13 retained in a running in position by at least one retaining dog  
14 carried in an opening provided on the outer mandrel adjacent the  
15 upper extent thereof.

16  
17 28. The method of claim 27, wherein the inner mandrel is provided  
18 with a recess for receiving the at least one retaining dog,  
19 movement of the retaining dog into the recess serving to allow  
20 movement of the collet housing axially downward relative to the  
21 outer mandrel whereby the collet fingers can engage a collet latch  
22 housing.

23  
24 29. The method of claim 28, wherein the collet latch housing is  
25 connected to a slip guide which underlies the gripping slips in the  
26 set position, the connection to the slip guide being severable by  
27 upward axial movement of the collet housing, thereby allowing the  
28 slip guide to be moved from beneath the gripping slips whereby the  
29 gripping slips can be returned to the start position.

1 30. The method of claim 29, wherein the slip guide includes upper  
2 collet fingers which are initially retained in a running in  
3 position by an interior surface of the collet latch housing and  
4 wherein the collet latch housing has an internal profile for  
5 receiving the slip guide collet fingers upon upward axial movement  
6 effected by the engagement of the collet housing collet fingers  
7 with the collet latch housing.

8  
9 31. The method of claim 30, wherein the collet latch housing is  
10 initially connected to the slip guide by a plurality of shear  
11 screws, the shear screws being severable by upward tension exerted  
12 on the collet latch housing by the collet housing.

1                                   **ABSTRACT OF THE DISCLOSURE**

2

3           An electro-mechanical wireline assembly as shown for anchoring

4   a wireline tool string in place during a wellbore under balanced

5   well conditions. The assembly includes an upper connection for

6   connection to the wireline leading to the well surface and a lower

7   connector for engaging a wireline tool. An outer mandrel is

8   attached to the lower connector. An inner mandrel is carried at

9   least partly within the outer mandrel and is capable of axial

10  movement within the outer mandrel. A slip gripping assembly is

11  carried on the outer mandrel and includes slips which are normally

12  biased radially inward but which can be moved radially outward for

13  engaging a surrounding wellbore and holding the wireline tool

14  string in place. An electric motor assembly is carried on the

15  wireline assembly between the upper and lower connectors. The

16  electric motor assembly is actuatable by an electric current supplied

17  from the well surface through the wireline to effect axial movement

18  of the inner mandrel relative to the outer mandrel to expand the

19  gripping slips in a radial direction between a start position and

20  a set position. The electric motor assembly can be switched in

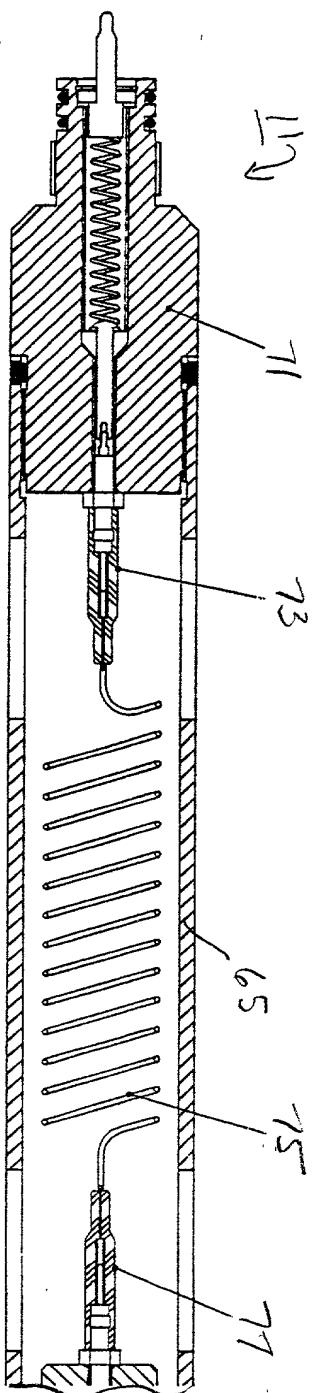
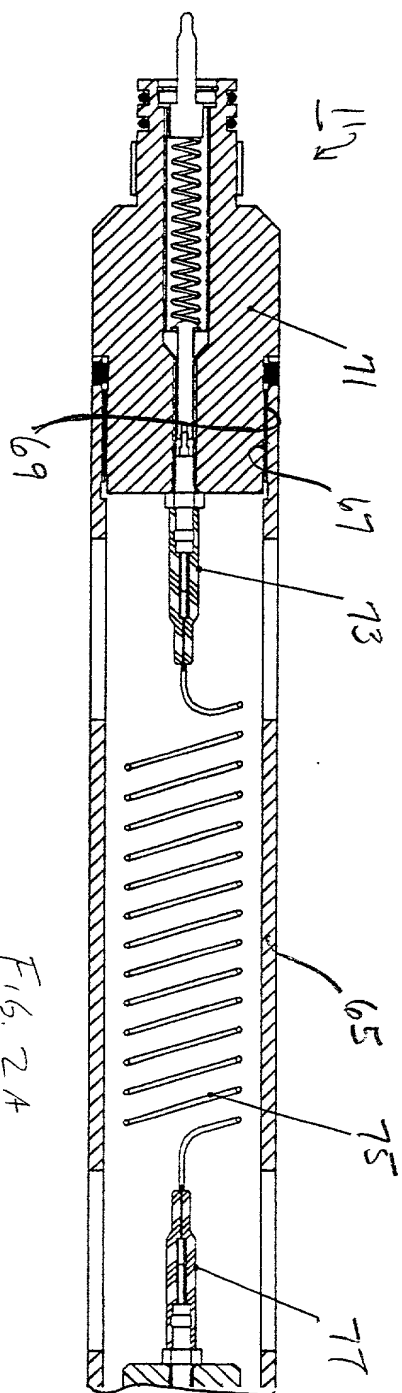
21  order to reverse the direction of axial movement of the inner

22  mandrel relative to the outer mandrel to retract the gripping slips

23  and return the slips to the start position. A back-up manual

24  release means is provided for manually retracting the gripping

25  slips radially inward upon completion of wellbore operations.



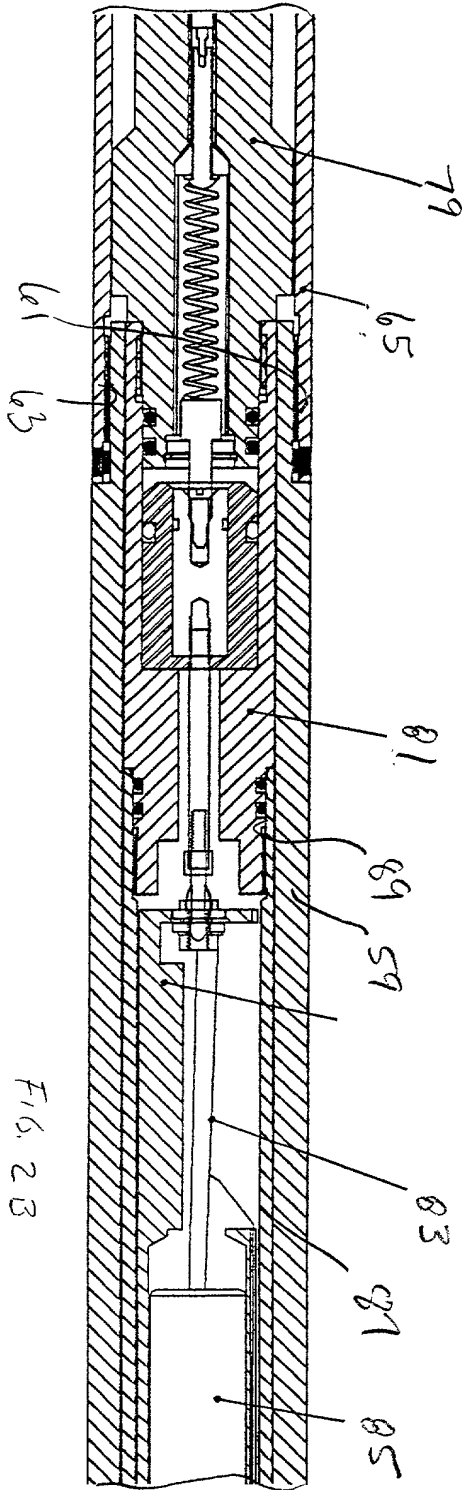


FIG. 2B

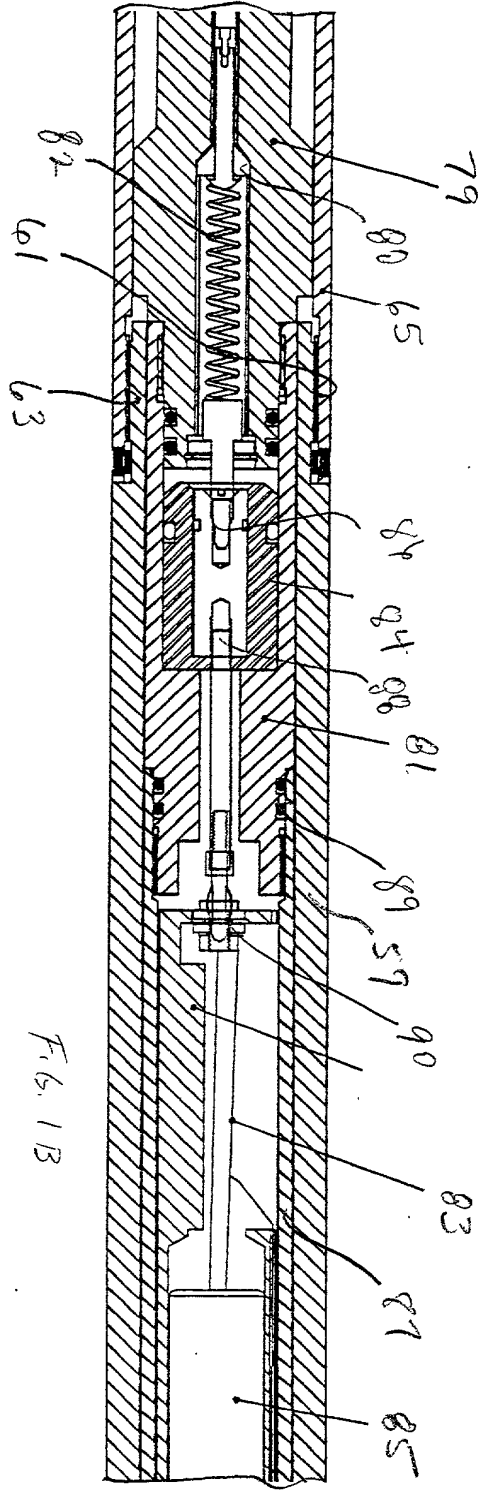


FIG. 1B

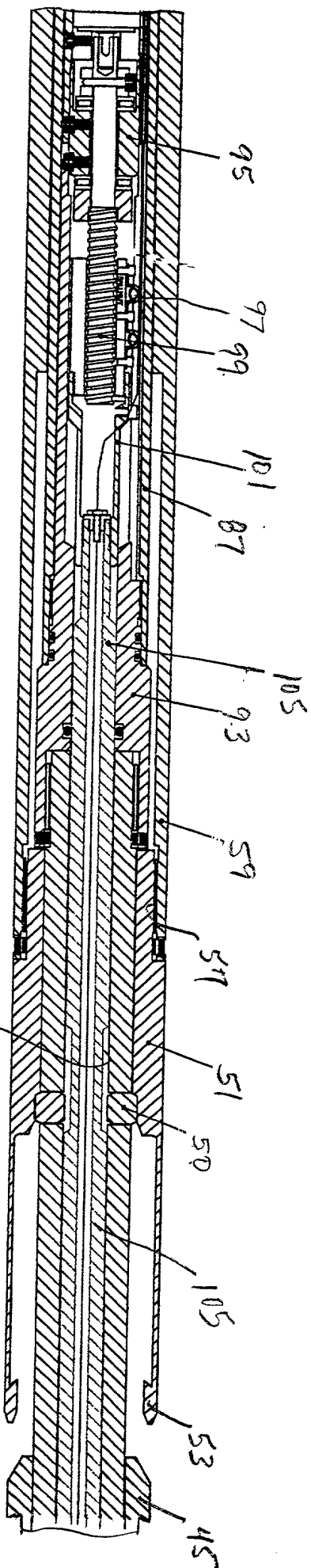


FIG. 2C

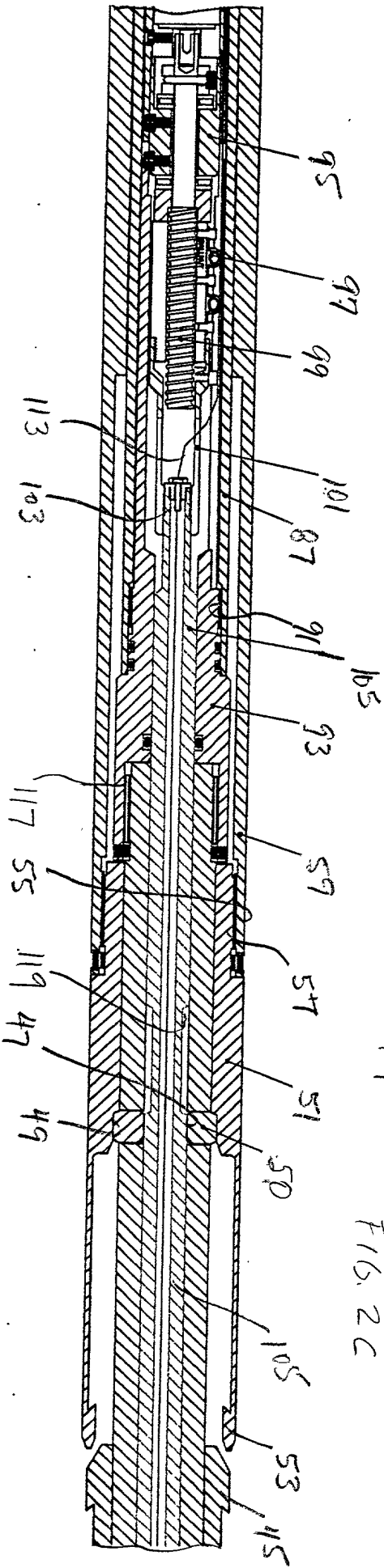
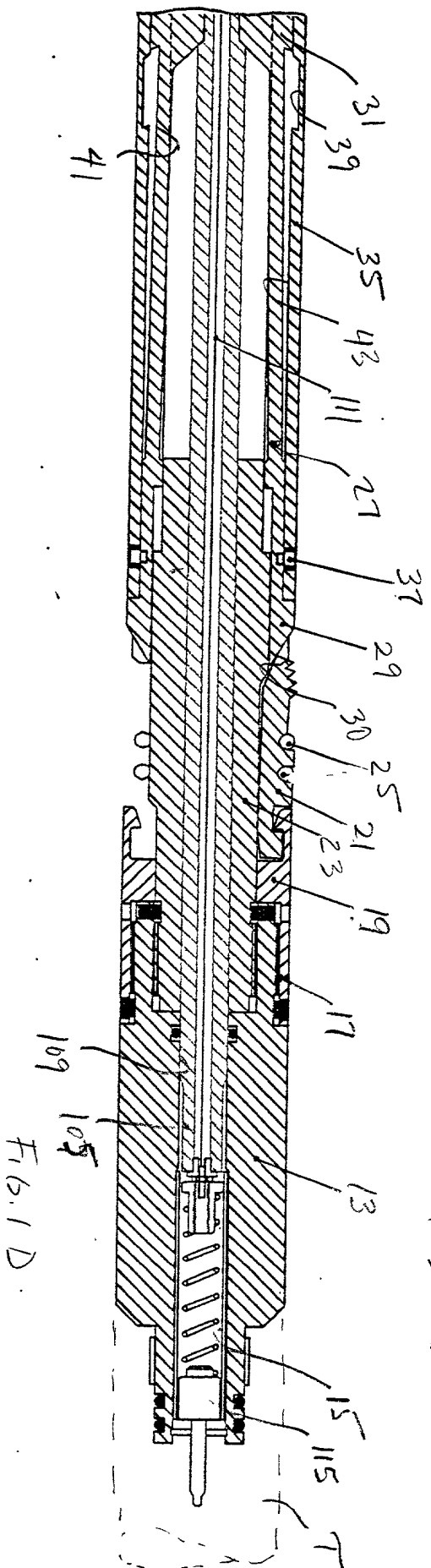
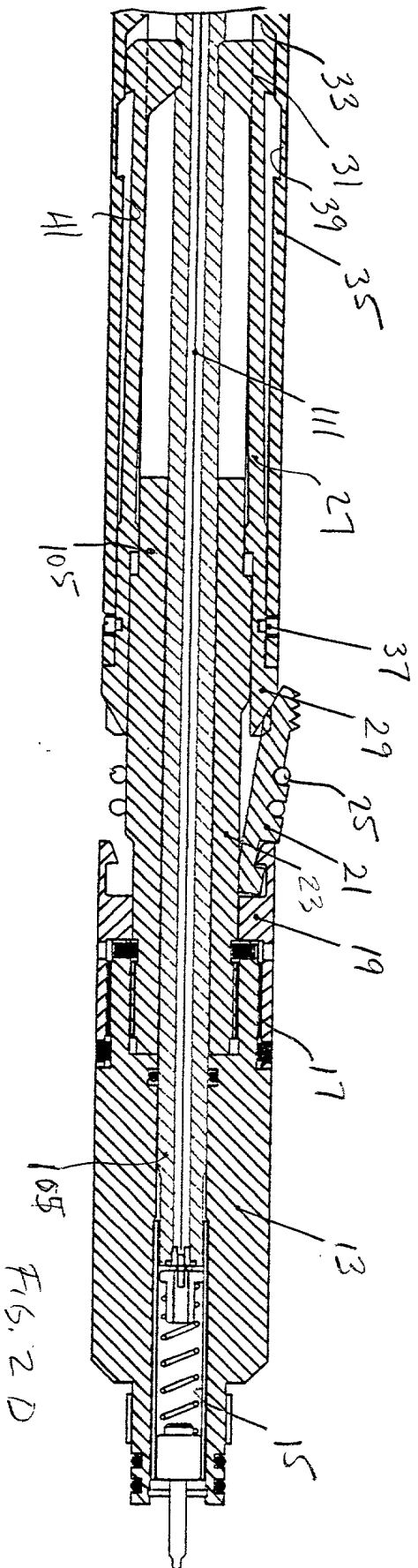
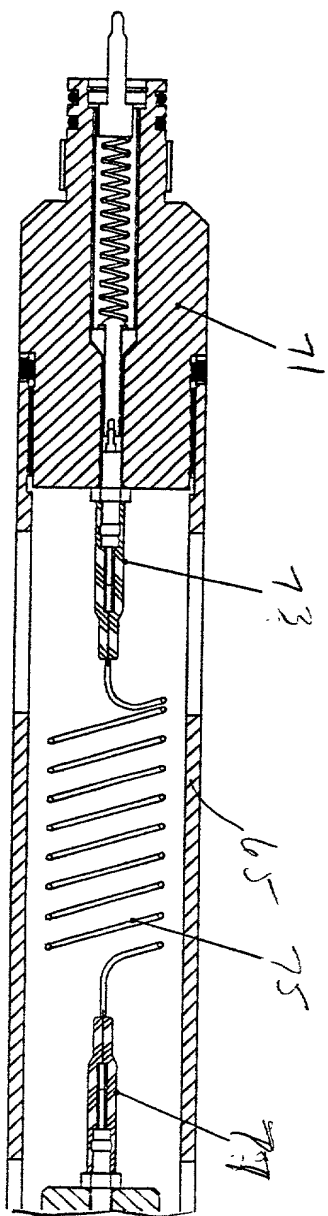
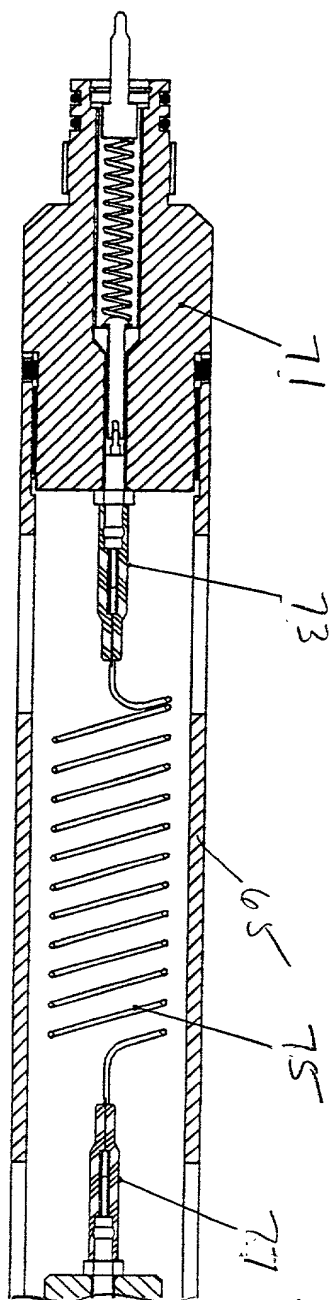


FIG. 1C







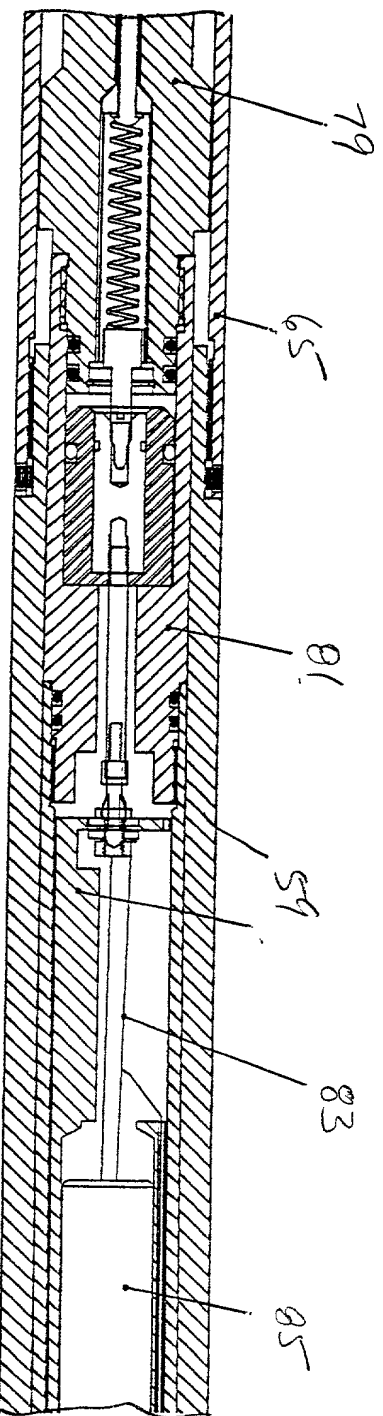


FIG. 4B

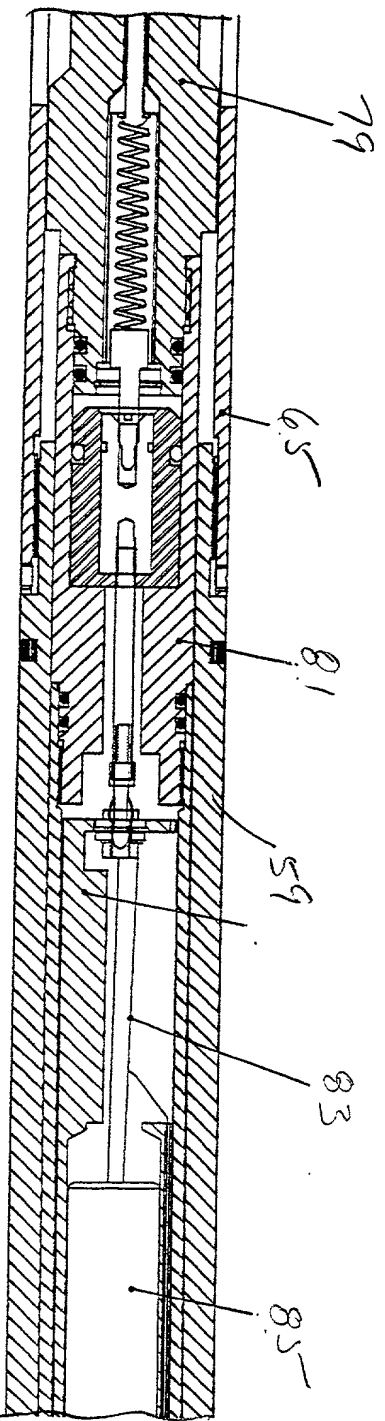


FIG. 3B

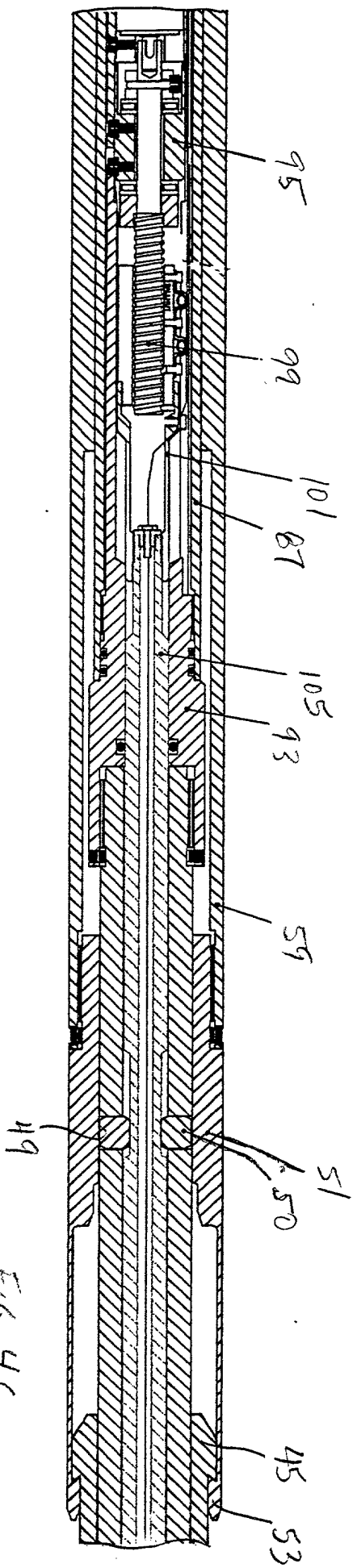


FIG. 4C

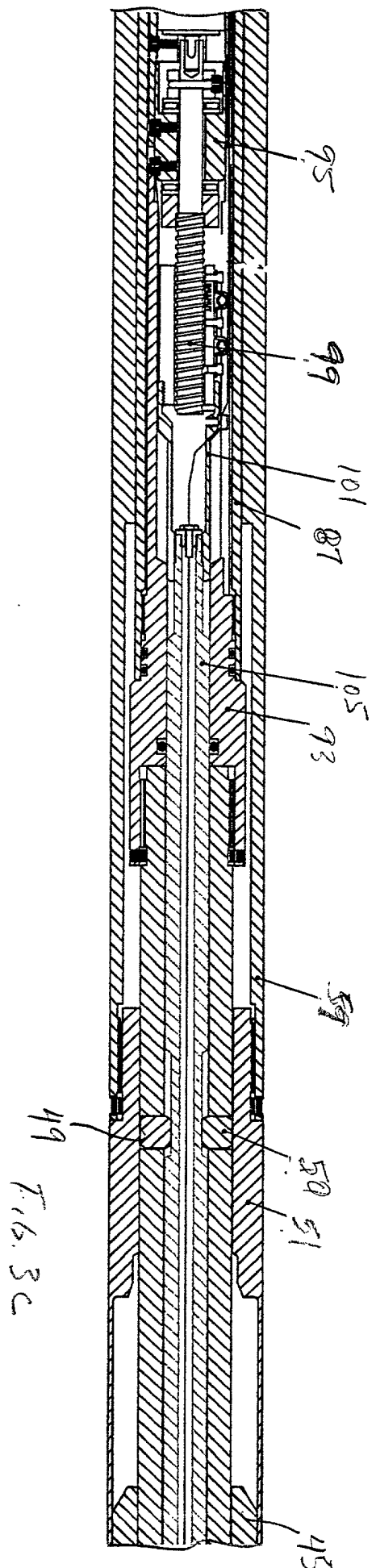
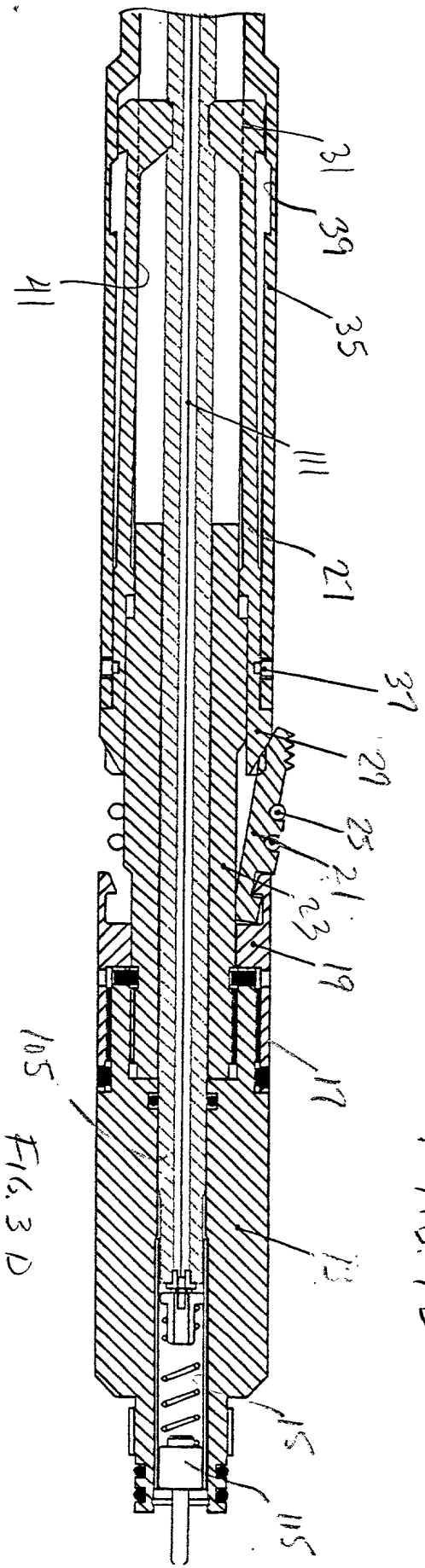
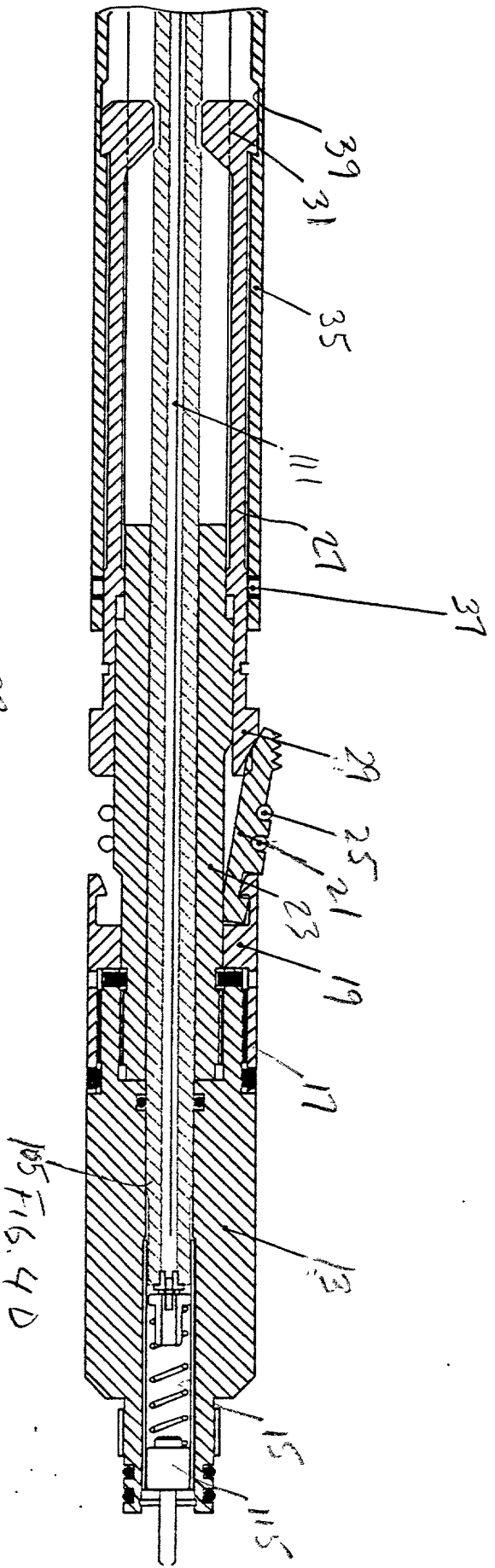


FIG. 3C



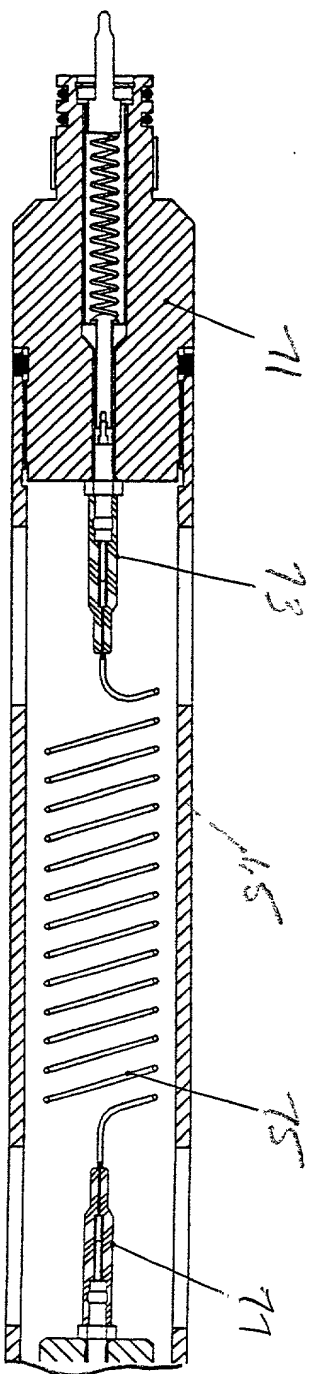


FIG. 5A

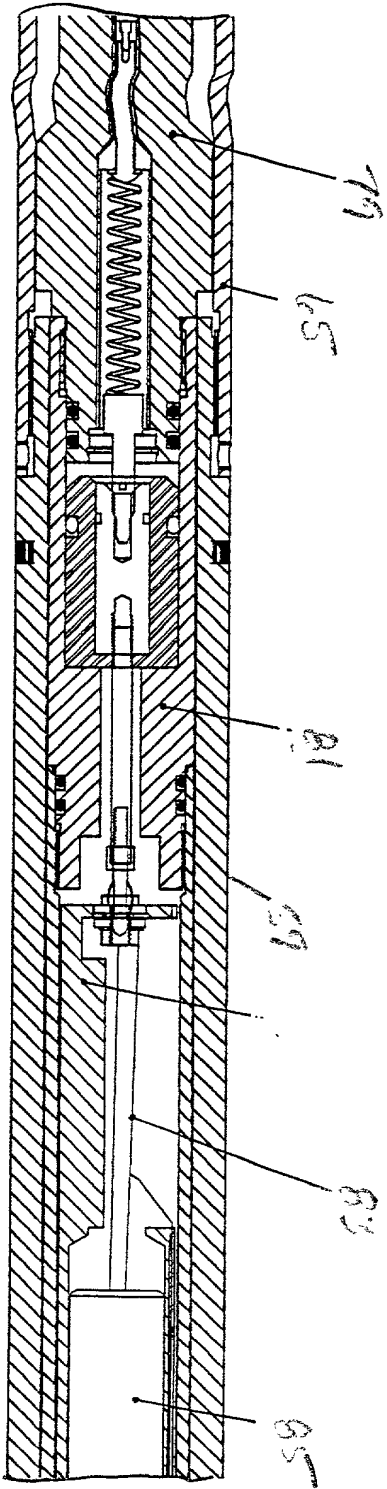


FIG. 5B

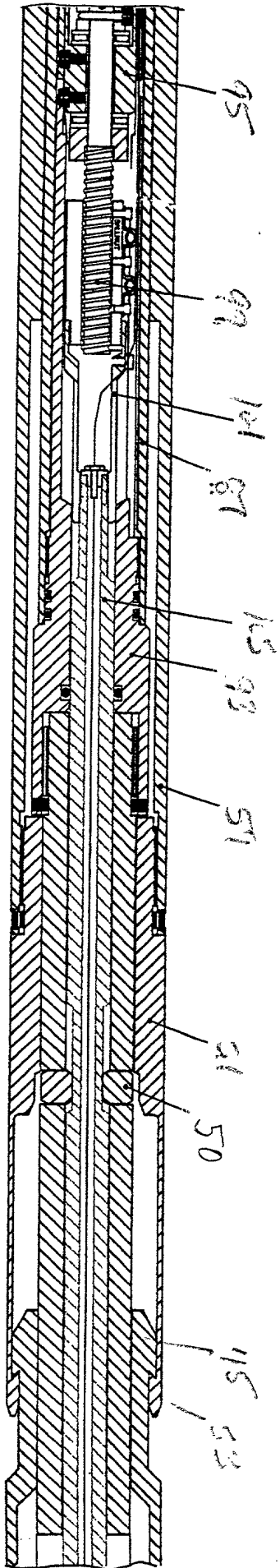


FIG. 5C



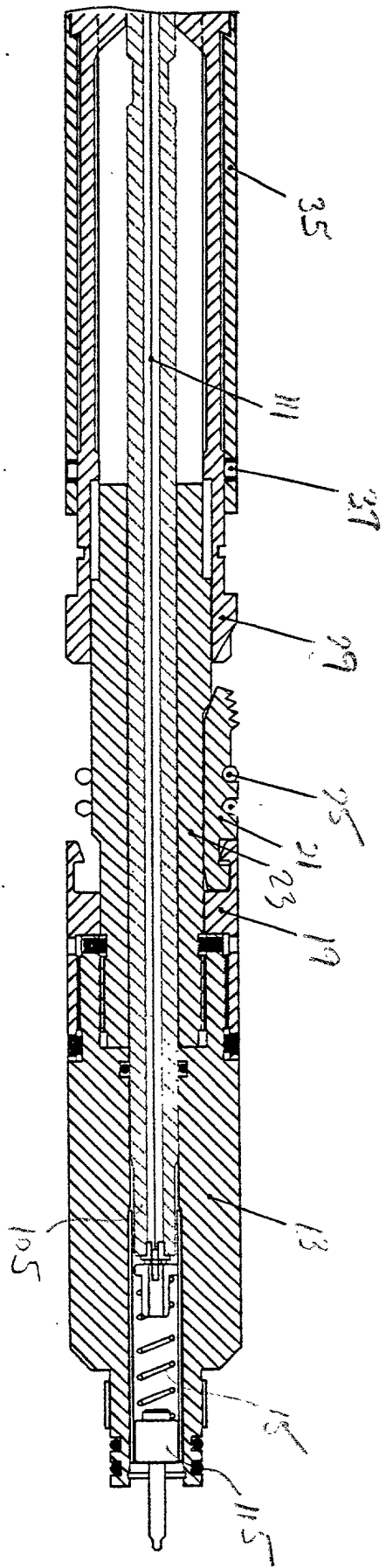
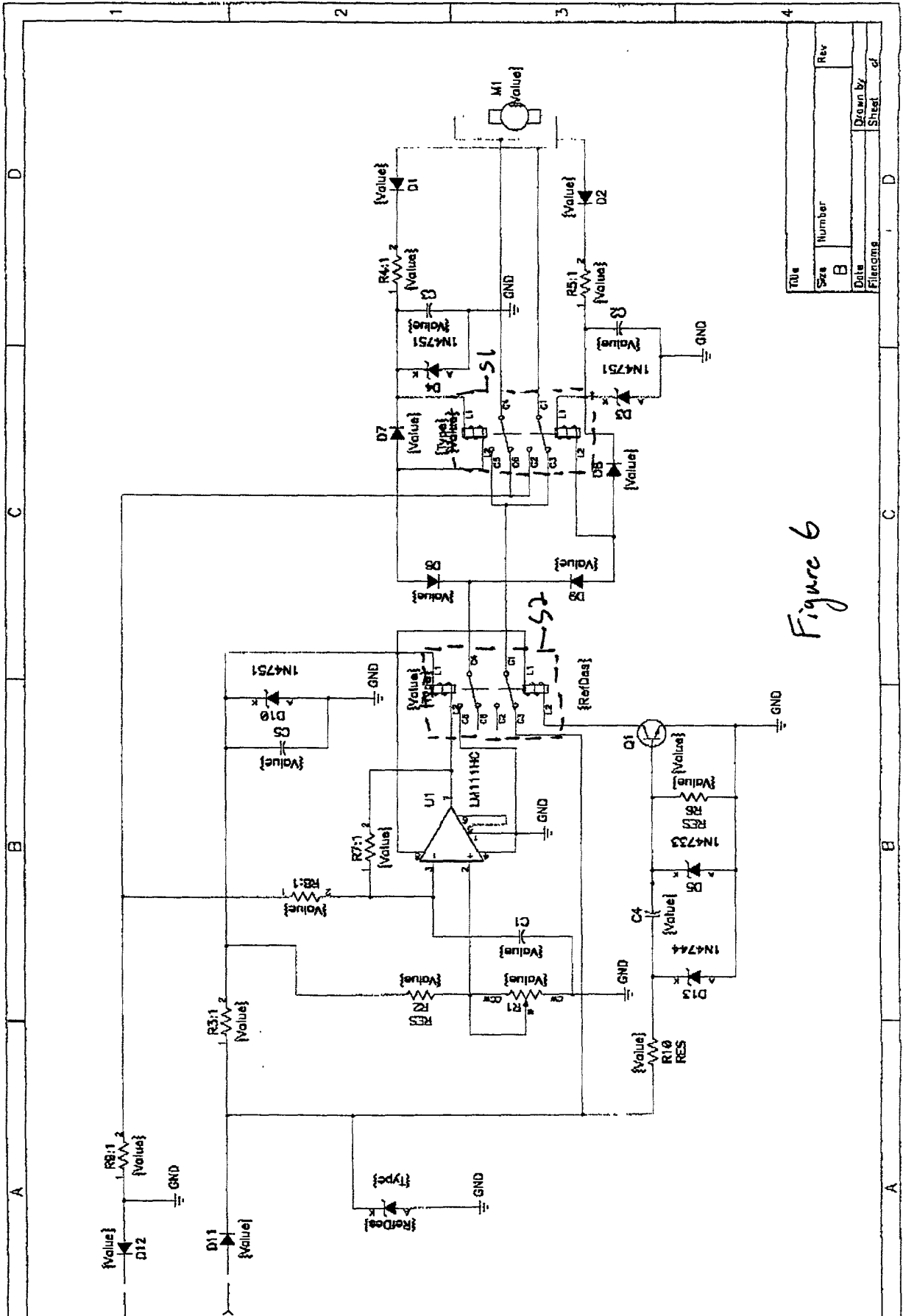


FIG. 5D

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